

# Generic FMS Platform for Evaluation of Autonomous Trajectory-Based Operation Concepts, Phase I

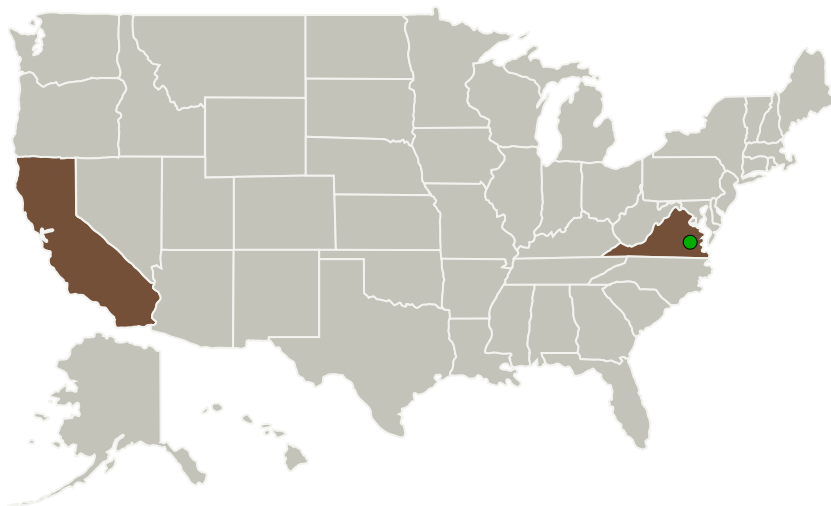
Completed Technology Project (2015 - 2015)



## Project Introduction

The objective of this research is to create a generic advanced Flight Management System (FMS) platform that could be used for evaluation of autonomous trajectory-based operation concepts. The research addresses the following deficiencies: most FMSs have limited advanced features; are specific to a single aircraft type; expensive and protected by FMS manufacturers. The proposed FMS platform will enable users to deploy a wide array of autonomy enabling FMS features by the click of a button. Some of the proposed features include: (i) air-ground & inter-aircraft trajectory negotiation, (ii) 4D Trajectory-Based Operations (4DTBO), (iii) high-fidelity wind modeling for improved predictability, (iii) trajectory planning options based on environmental and efficiency considerations, and (iv) advanced guidance modes such as Required Time of Arrival (RTA) and 4DFMS. A key feature of the proposed research is the integration of this platform and its features with NASA's Multi-AirCRAFT Simulation (MACS) platform. Phase I research will identify the complete array of features for possible inclusion in this platform. Moreover, Phase I will demonstrate select features through the interface to MACS. Phase II research will elevate the technology readiness level suitable for deployment in Human-In-The-Loop simulation pilot stations.

## Primary U.S. Work Locations and Key Partners



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## Table of Contents

Project Introduction	1
Primary U.S. Work Locations and Key Partners	1
Project Transitions	2
Images	2
Organizational Responsibility	2
Project Management	2
Technology Maturity (TRL)	3
Technology Areas	3
Target Destinations	3

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Organizations Performing Work	Role	Type	Location
Optimal Synthesis, Inc.	Lead Organization	Industry Small Disadvantaged Business (SDB)	Los Altos, California
● Langley Research Center(LaRC)	Supporting Organization	NASA Center	Hampton, Virginia

## Primary U.S. Work Locations

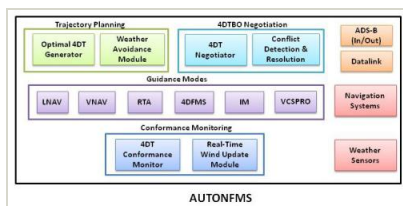
California	Virginia
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## Project Transitions

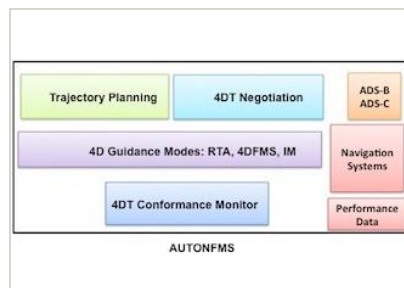
**June 2015:** Project Start**December 2015:** Closed out**Closeout Documentation:**

- Final Summary Chart(<https://techport.nasa.gov/file/138892>)

## Images

**Briefing Chart**

Generic FMS Platform for Evaluation of Autonomous Trajectory-Based Operation Concepts Briefing Chart (<https://techport.nasa.gov/image/132534>)

**Final Summary Chart Image**

Generic FMS Platform for Evaluation of Autonomous Trajectory-Based Operation Concepts, Phase I Project Image (<https://techport.nasa.gov/image/134419>)

## Organizational Responsibility

**Responsible Mission Directorate:**

Space Technology Mission Directorate (STMD)

**Lead Organization:**

Optimal Synthesis, Inc.

**Responsible Program:**

Small Business Innovation Research/Small Business Tech Transfer

## Project Management

**Program Director:**

Jason L Kessler

**Program Manager:**

Carlos Torrez

**Principal Investigator:**

Veera V Vaddi

**Co-Investigator:**

Veera Vaddi

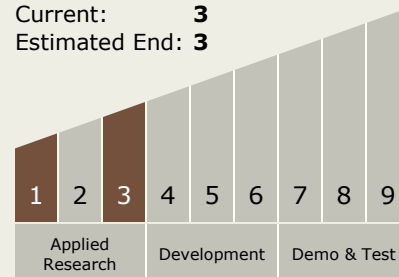
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## Technology Maturity (TRL)

Start: **1**  
Current: **3**  
Estimated End: **3**



## Technology Areas

### Primary:

- TX10 Autonomous Systems
  - └ TX10.3 Collaboration and Interaction
    - └ TX10.3.3 Goal and Task Negotiation

## Target Destinations

The Sun, Earth, The Moon, Mars, Others Inside the Solar System, Outside the Solar System